

Consistency of the Fittest: Towards Dynamic Staleness Control for Edge Data Analytics

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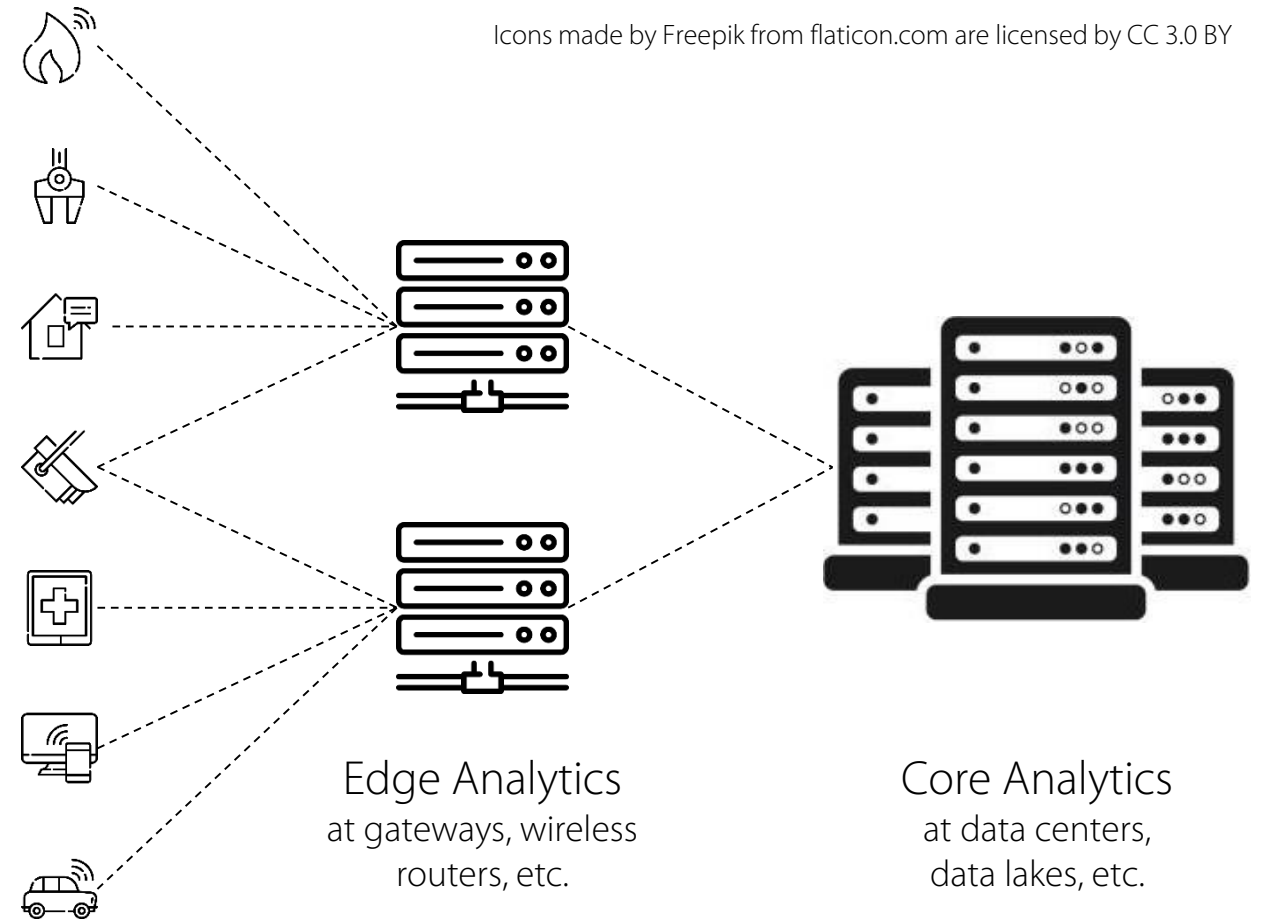
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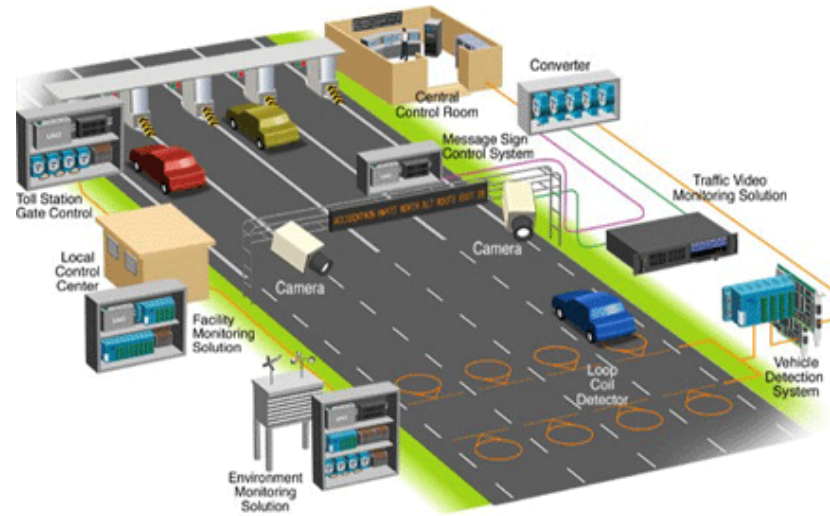
Two main driving forces:

- Faster response to detected events
 - Edge nodes are in close proximity.
 - Network latency is low.
- Less data transfer / storage
 - Edge nodes can filter out raw data.
 - Only valuable information is transferred.



Common Features:

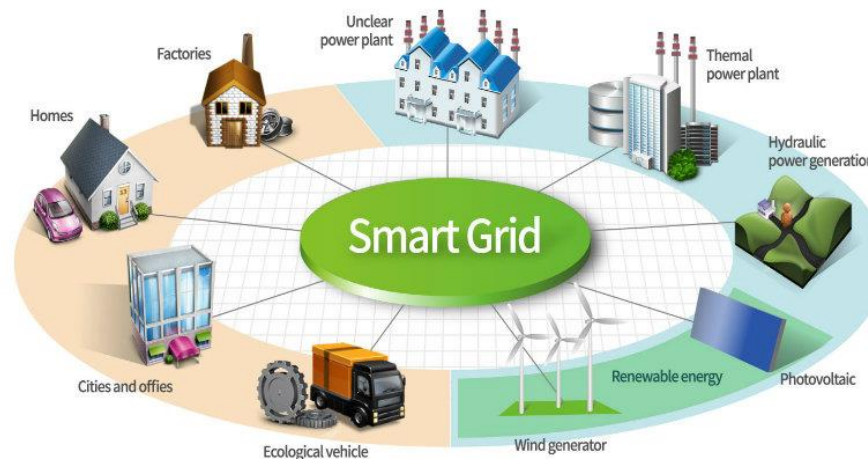
- Time-sensitive
- Data-intensive
- Distributed
- Non-stationary



Intelligent Traffic Control



Computational Advertising

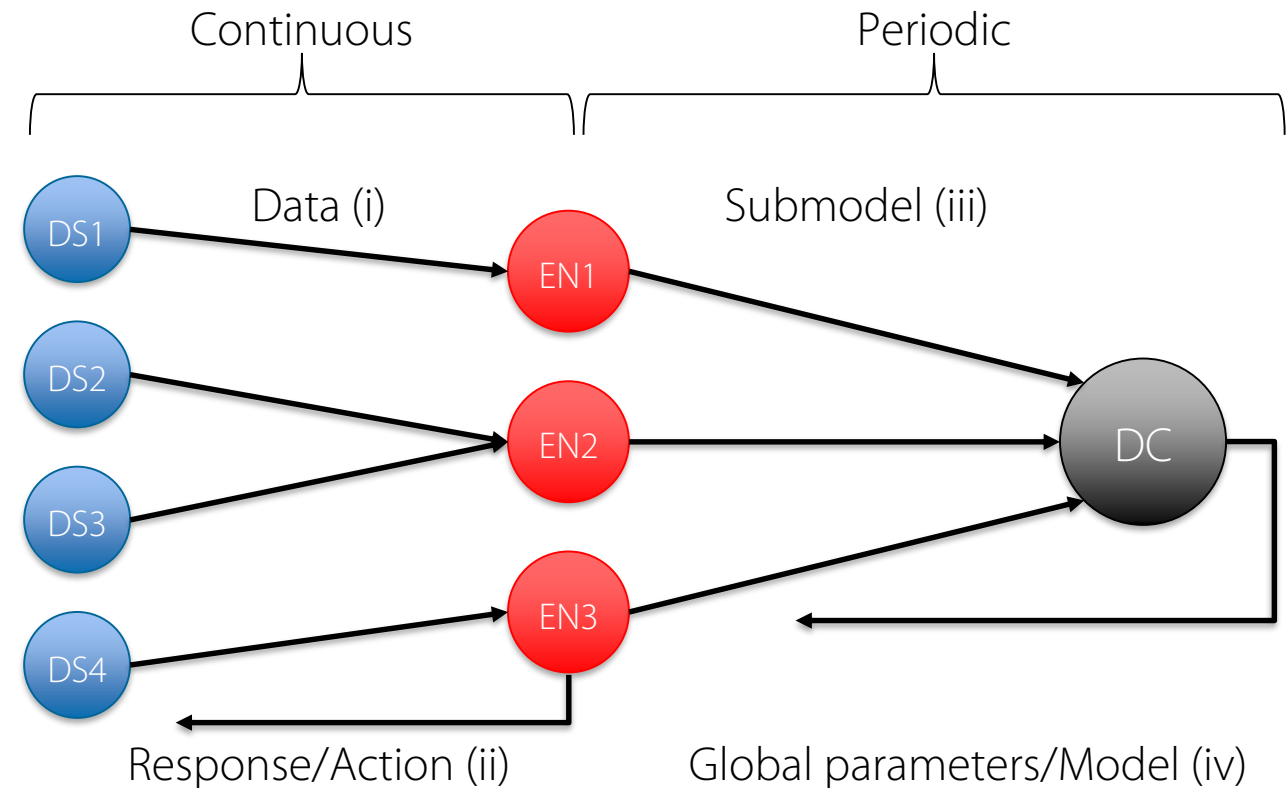


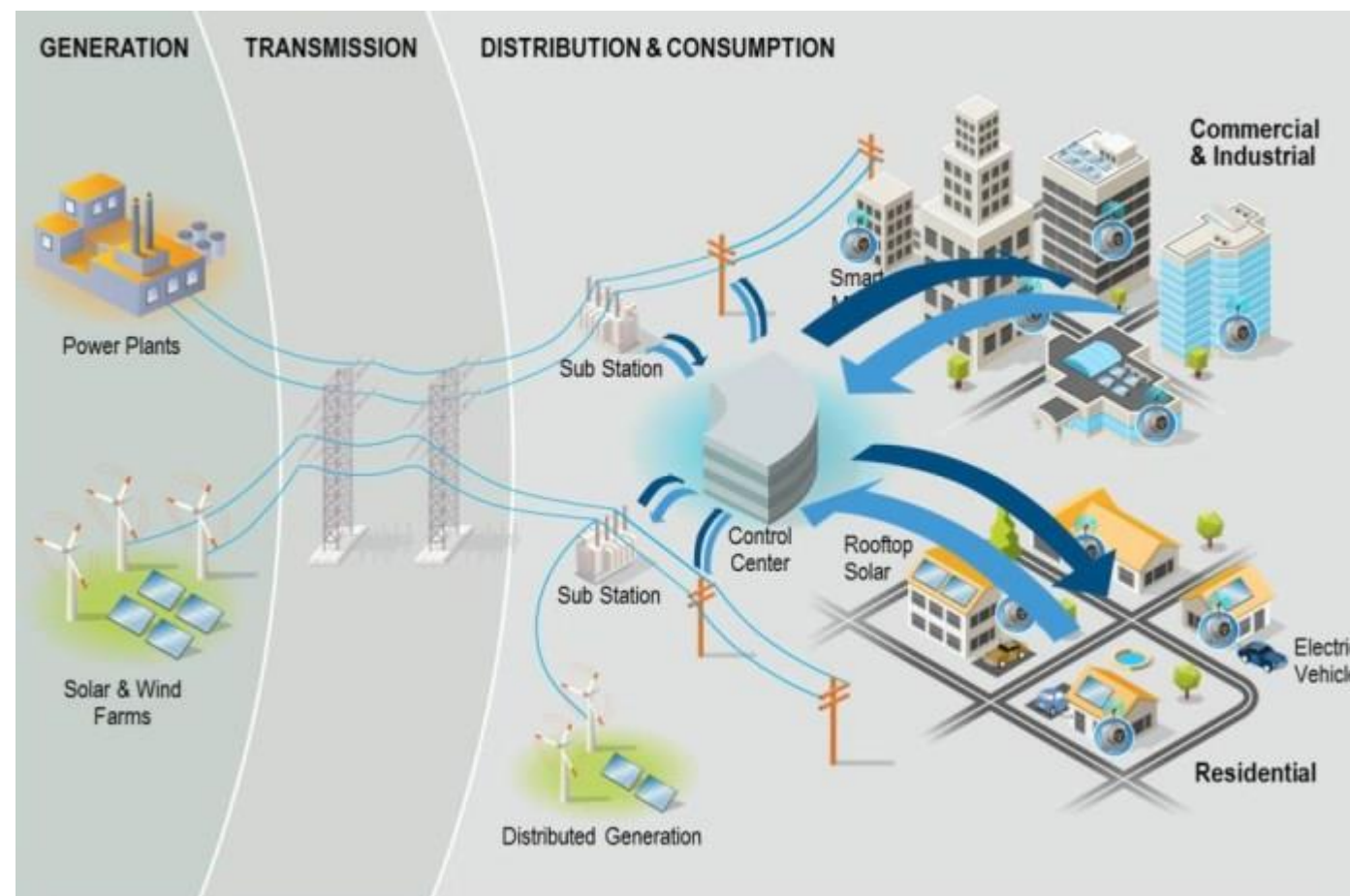
Transactive Energy Control



Spam or Fraud Detection

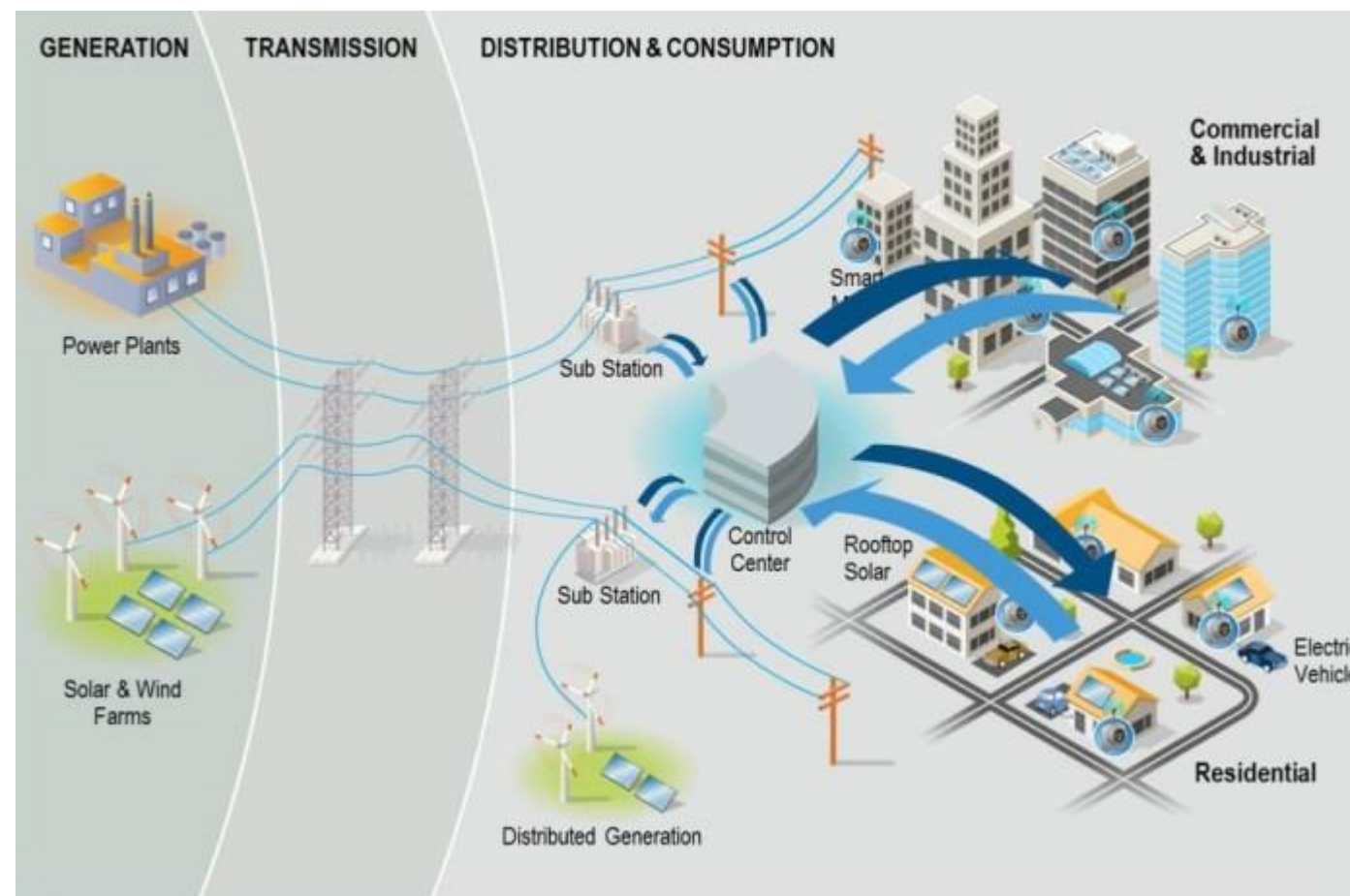
- i. Data from distributed streams are collected in nearby edge nodes.
- ii. Decisions based on local ML model and current data are sent back to the actuators **[inference]**.
- iii. Local model is updated online with current data **[training]** and sent to a parameter server.
- iv. A global model is formed and it replaces stale or incomplete models at edge nodes.





Smart Grid architecture. Image source: ecoideaz.com

- *“Dynamic balance of supply and demand across the entire electrical infrastructure”*
- Supply/Demand forecasting is a critical issue
- DOML & edge is a natural fit
 - coping with spikes in demand,
 - dynamically controlling voltage to reduce losses,
 - increasing the utilization of generators.

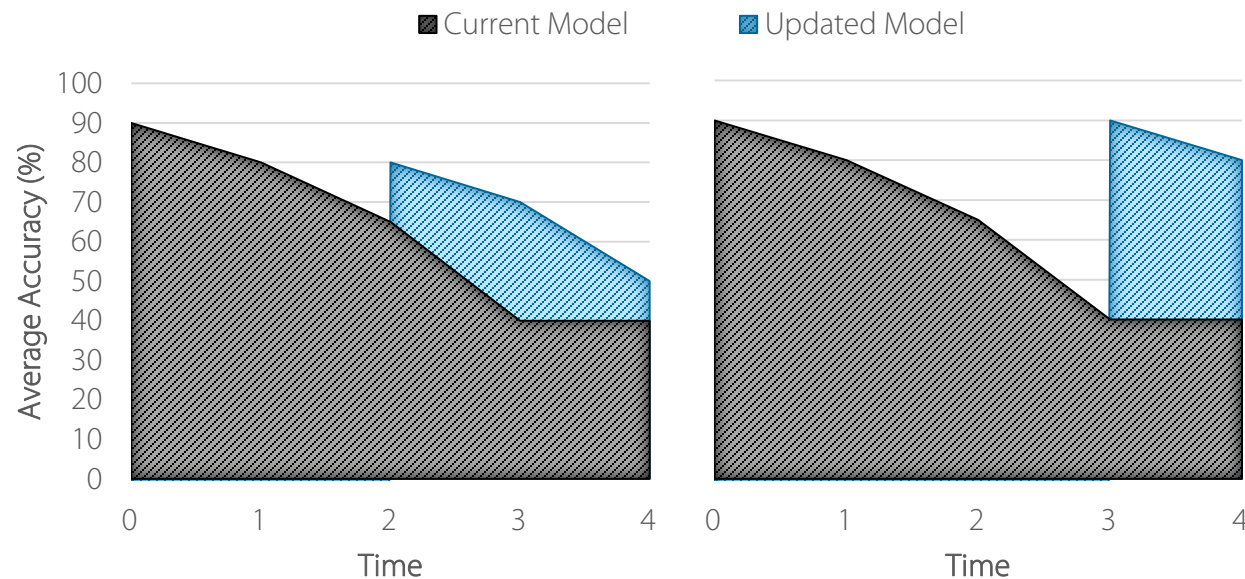
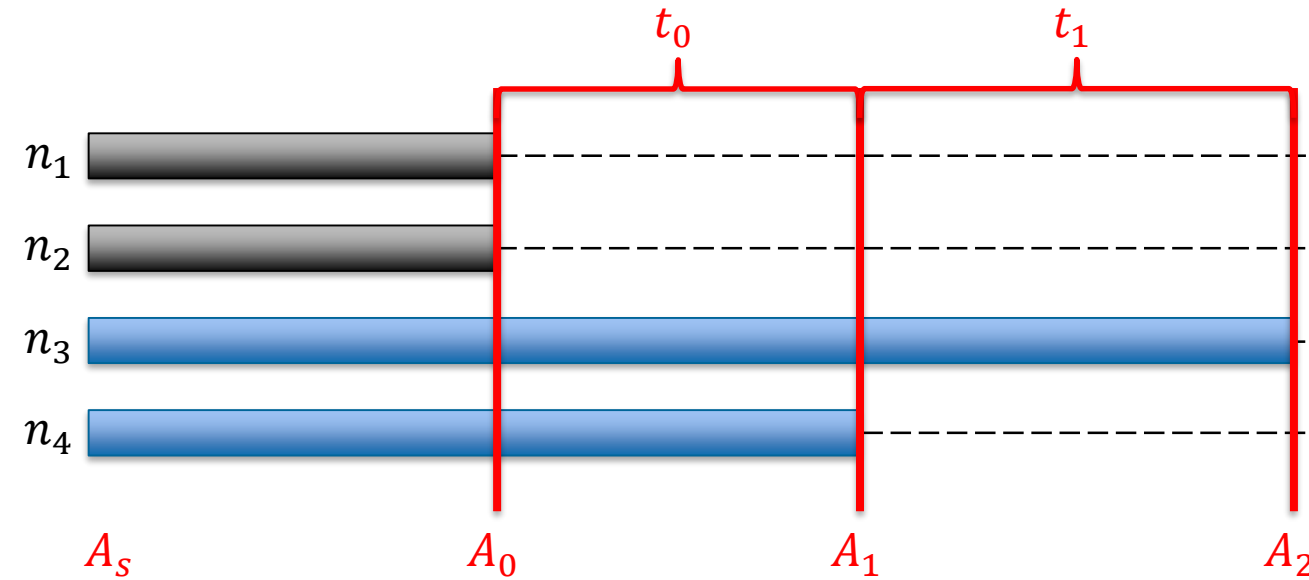


Smart Grid architecture. Image source: ecoideaz.com

- Non-stationarity arises from:
 - **Structural changes:** joining or leaving producers, forming or dissolving links, technological advances, etc.
 - **Quantitative changes:** evolving consumption habits, unexpected events, seasonality, etc.
- Updates from edge nodes arrive **asynchronously**.
- Not all updates have the same **significance**.

How many responses to wait for before updating global model and sending it to edge nodes?

- Quorum size
- Staleness bound
- Dynamic periodicity



$$\underset{i}{\text{maximize}} \quad \int_0^{\tau_i} A_s(x) dx + \int_{\tau_i}^{\epsilon} A_i(x) dx$$

$$\text{where} \quad \tau_i = \sum_{j=0}^{i-1} t_j$$

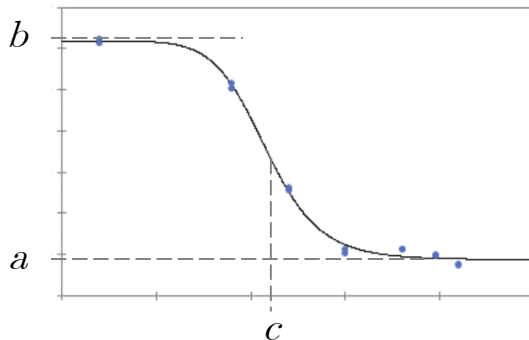
$$\text{subject to} \quad i \in \mathbb{Z}, 0 \leq i \leq k.$$

$$A(x) = C(x)A$$

Characteristic Function

- Depends on ML algorithm
- One time curve fitting with sample data
- Four parameter logistic regression (Sigmoidal)
- Range normalized to $[0,1]$

$$y = a + \frac{b - a}{1 + \left(\frac{x}{c}\right)^d}$$



Initial Accuracy

- Depends on local conditions
- Time series prediction (ARIMA)
- Based on previous improvement rates

$$R_i = \frac{A_i - A_{i-1}}{A_{i-1}}$$

maximize_i

$$\int_0^{\tau_i} A_s(x) dx + \int_{\tau_i}^{\epsilon} A_i(x) dx$$

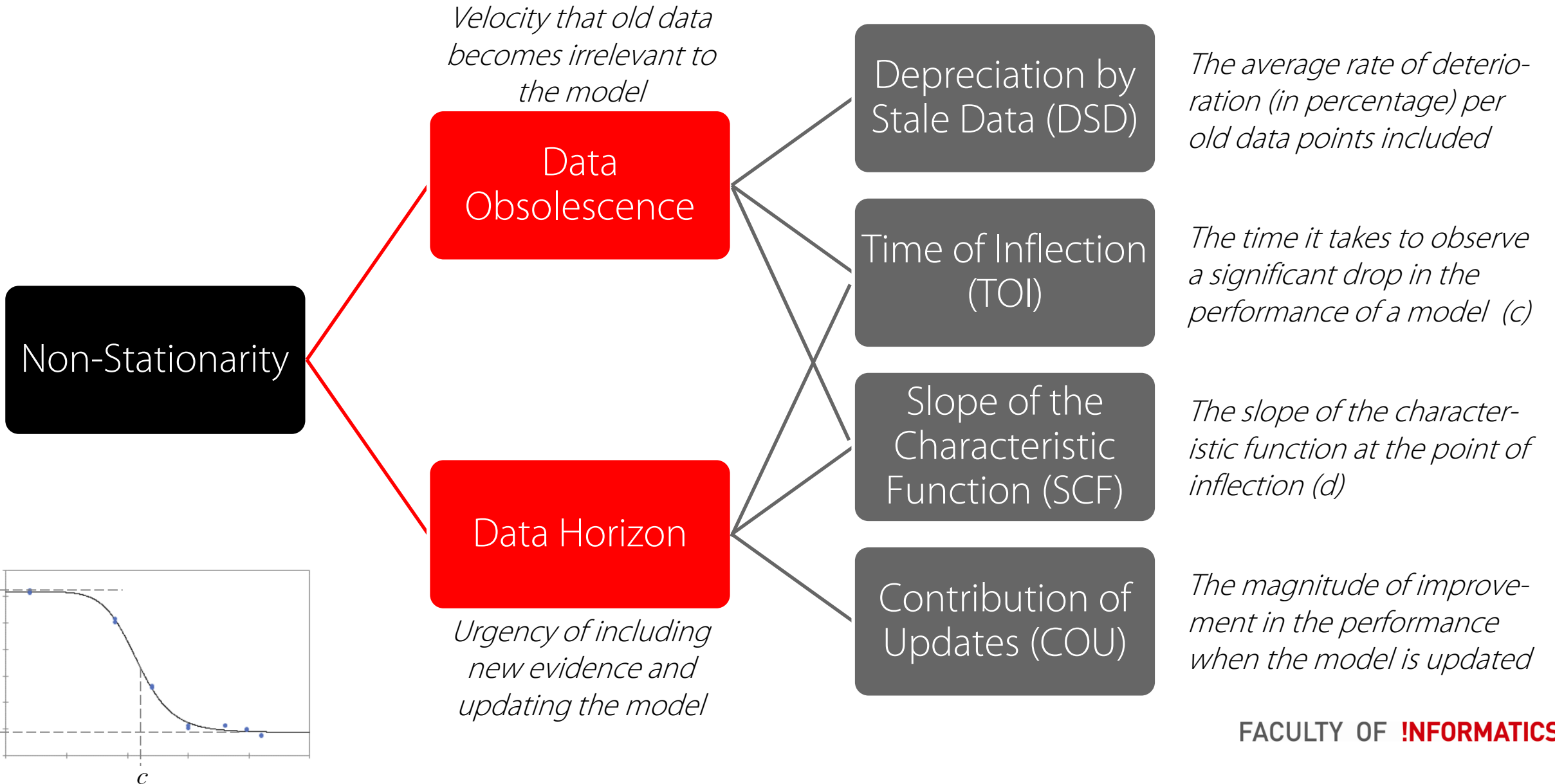
where

$$\tau_i = \sum_{j=0}^{i-1} t_j$$

subject to $i \in \mathbb{Z}, 0 \leq i \leq k.$

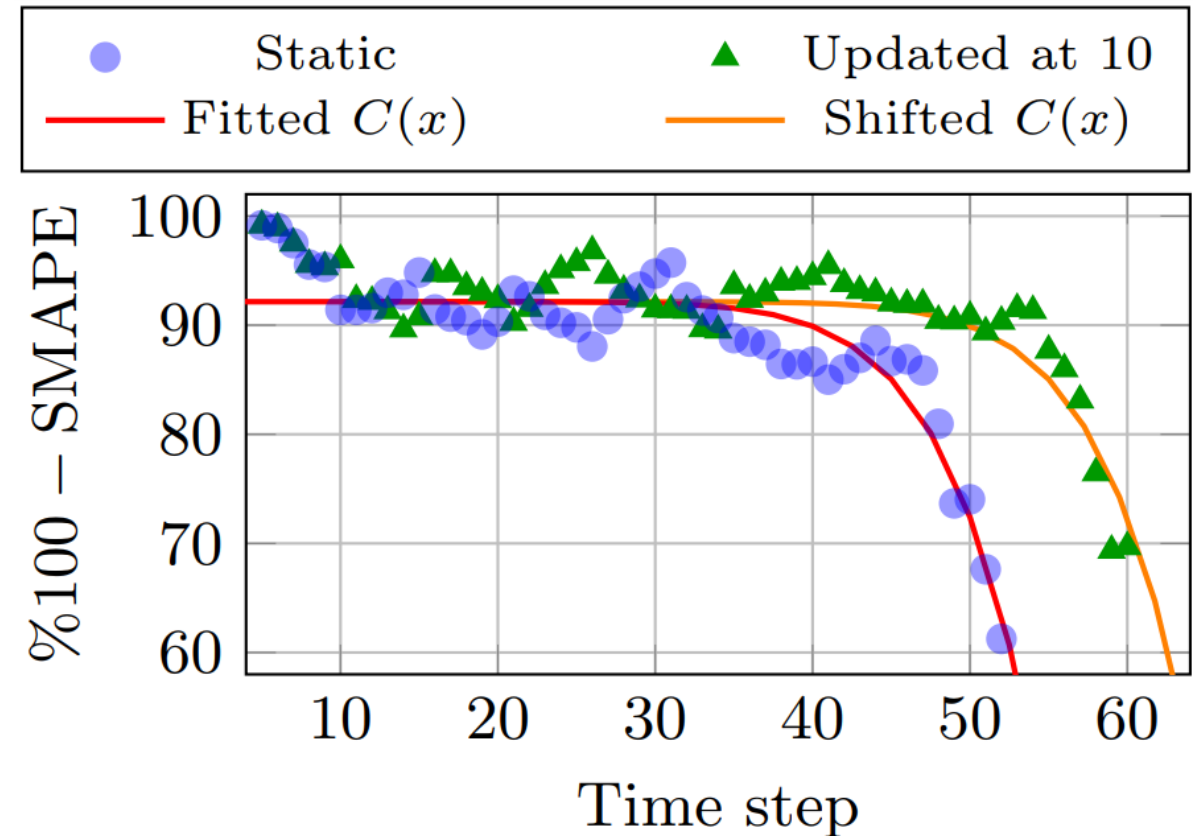
Response Time

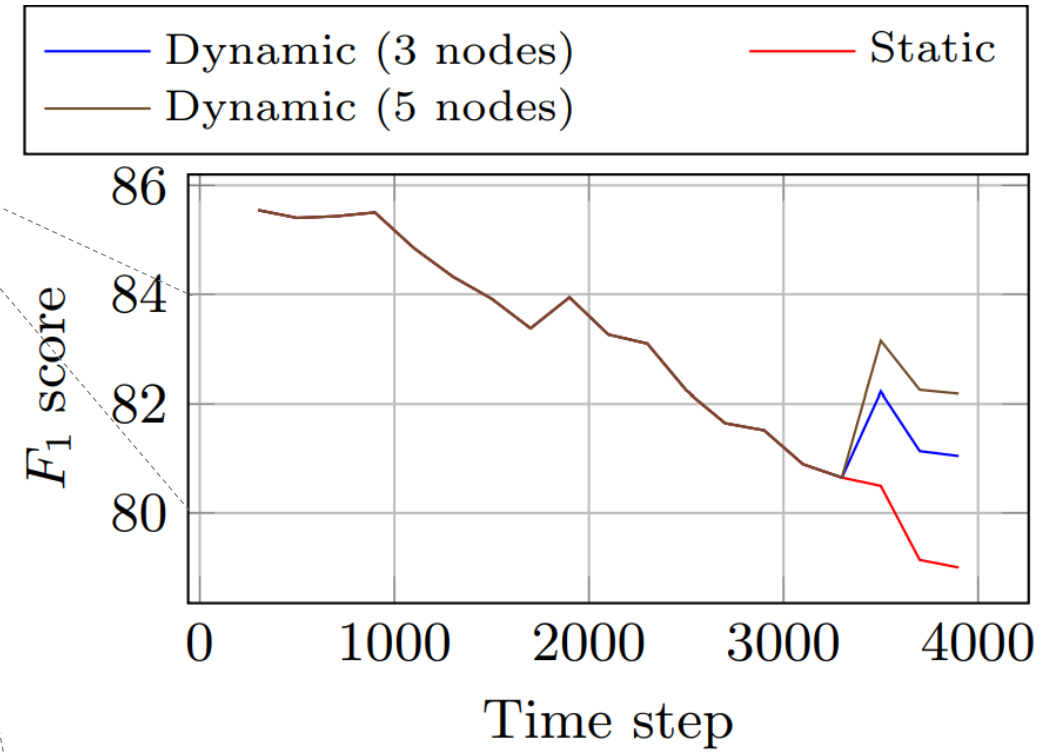
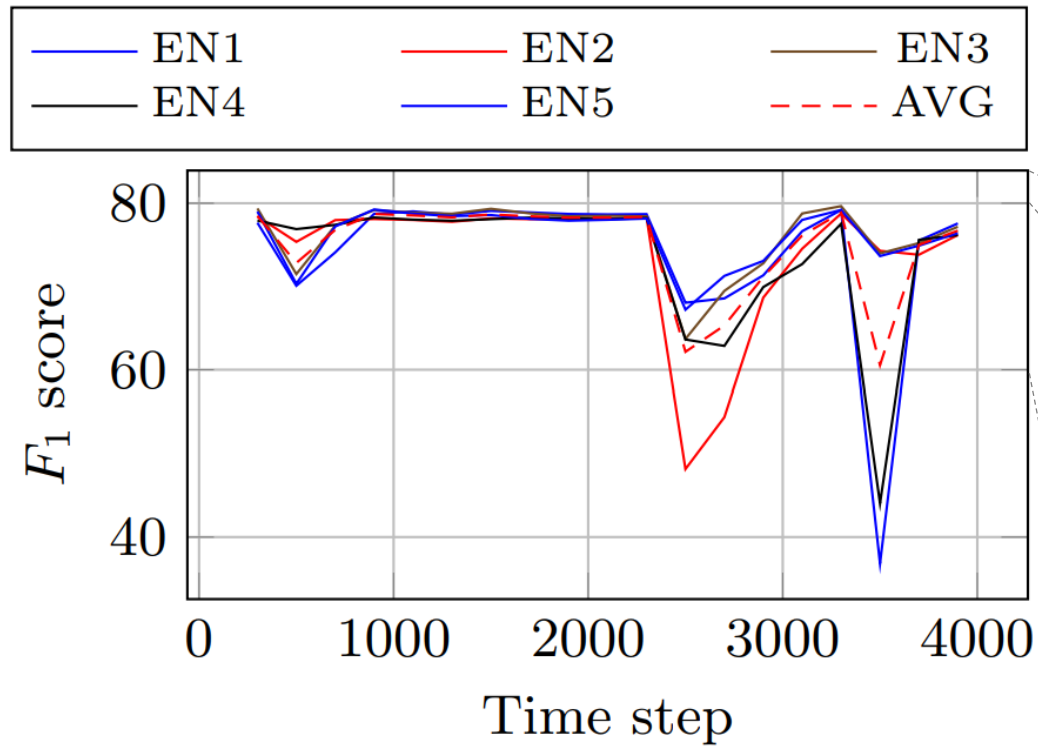
- Depends on local conditions
- Support Vector Machine regression
- Based on previous response times
- Works well for time-to-failure



- Elec2 data set
 - Electricity market of New South Wales
 - Forecasting electricity demand
 - SVM regression model
 - 100 half-hourly data points

- Further experiments:
 - DBN availability prediction of client computers with **SETI@Home** data set
 - Correlation of non-stationarity metrics





- Takeaways:
 - Edge computing is promising for implementing DOML.
 - Non-stationary is a major challenge. It is measurable.
 - Dynamic periodicity can be an effective solution.

- Future Work:
 - Extended evaluation on a real DOML system
 - Source of the problem: avoiding (or at least predicting) stragglers
 - Resource selection
 - Load distribution

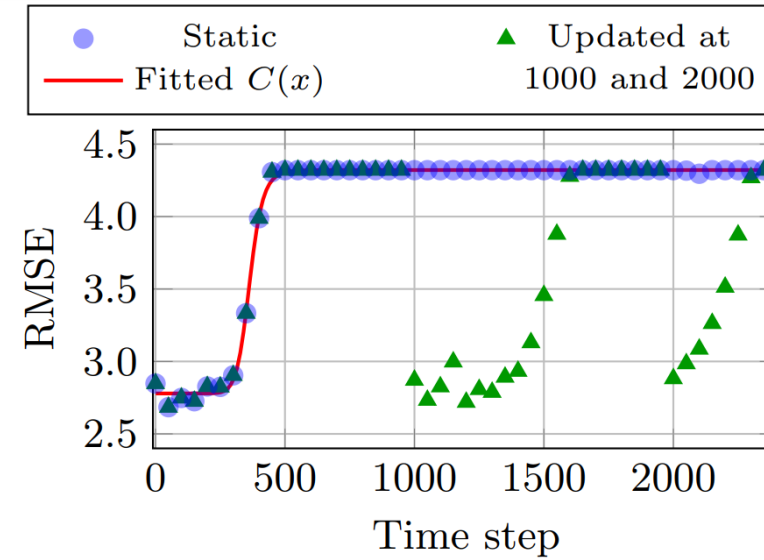
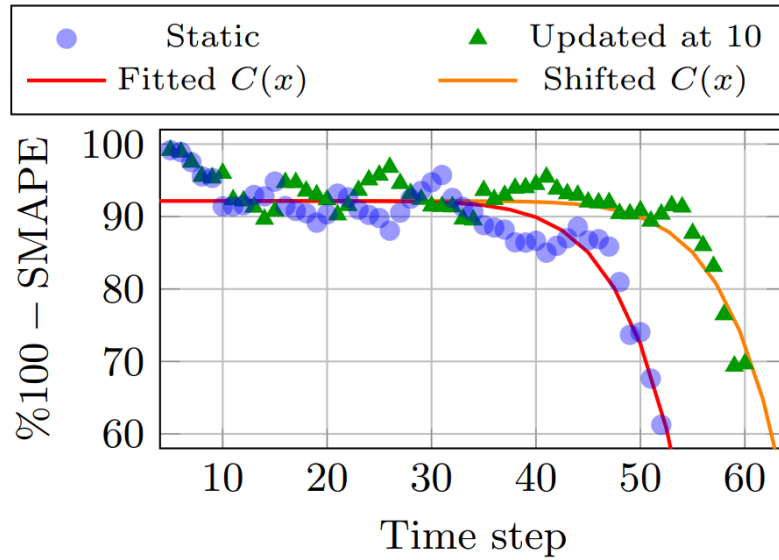
Thank you for your attention!

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DS	ML (#P)	SCF	TOI	COU	DSD
[11]	SVM (10)	6.702	91.682	8.244	22.49
[11]	SVM (15)	7.408	84.037	3.302	23.71
[11]	SVM (20)	8.264	78.034	10.32	24.81
[11]	SVM (40)	8.394	67.497	5.636	23.54
[11]	SVM (50)	10.97	37.941	3.738	25.38
[13]	DBN	14.27	363.83	32.00	2.430

	SCF	TOI	COU	DSD
TOI	-0.9879			
COU	-0.3849	0.4654		
DSD	0.8571	-0.7731	-0.1505	
#P	0.8212	-0.9489	-0.4506	0.6325